

Servosila Robotic Heads



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TABLE OF CONTENTS

| | |
|--------------------------------------------------------|----------|
| SERVOSILA ROBOTIC HEADS | 2 |
| SOFTWARE-DEFINED FUNCTIONS OF THE ROBOTIC HEADS | 2 |
| SPECIFICATIONS: ROBOTIC HEADS | 4 |
| DIMENSIONS OF ROBOTIC HEAD | 5 |
| DIMENSIONS OF DESKTOP ROBOTIC HEAD | 5 |
| OPERATOR CONTROL UNIT (OCU) | 6 |
| SPECIFICATIONS: OCU | 7 |
| ABOUT SERVOSILA | 8 |

Servosila Robotic Heads



The robotic heads are highly integrated, sensor rich, passively cooled, watertight yet powerful computers designed to serve as centralized control nodes of mobile robots. The robotic heads feature an internal DC-to-DC power regulator that enables them to draw power from onboard batteries or power generators.

The robotic heads are optimized for the following control applications:

- Outdoor Mobile Robots
- Service Robots
- Robotic Arms for Mobile Robots



Since the robotic heads combine a high-performance computer and a set of sensors in the same package, the amount of cabling is significantly reduced, installation simplified and maintenance streamlined. The robotic heads can be also taken off the robots and used as desktop testbed computers by developers of onboard software; an HDMI monitor port and a keyboard port are provided to simplify desktop-style use.

The robotic heads come with watertight sockets for connecting external payloads such as Servosila Servo Drives or a Thermal Vision Camera. The external payloads are controlled via CAN, Ethernet or USB onboard buses, and powered by a payload power supply line, - via the same watertight socket.

Software-Defined Functions of the Robotic Heads

The hardware configuration of the robotic head is specifically designed for the following tasks (depending on installed software):

- Remote control of a mobile robot with onboard video compression and streaming
- Controlling multiple servo drives, differential drive motors and other actuators, health checks and monitoring of servo drives via a CAN bus
- Automatic obstacle detection and avoidance using a laser scanner or/and a stereo vision system
- Visual object recognition, visual localization, and visual object tracking using multiple video cameras

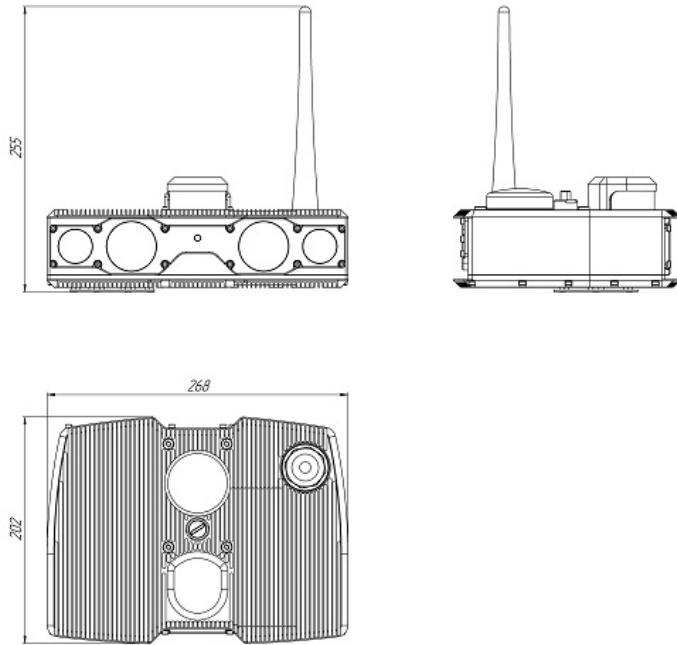
- Simultaneous Localization and Mapping (SLAM) via fusion and filtering of data coming from multiple sensors including a laser scanner, a stereo vision, a MEMS inertial measurement unit and a GPS/GLONASS receiver
- Path planning using a digital map created via a SLAM method
- Robotic arm control including inverse kinematics and 3D motion planning
- Automatic self-leveling of a mobile robot
- Self-Health Testing.



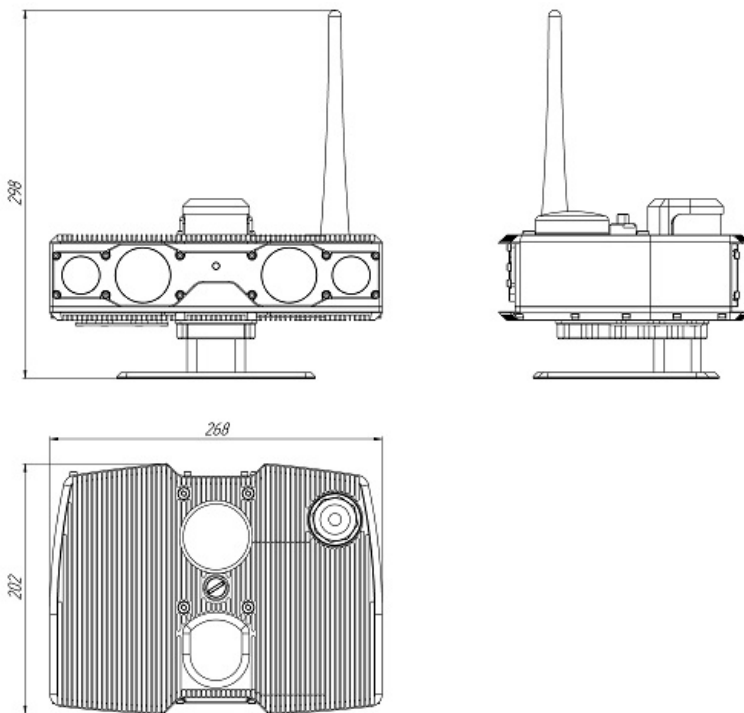
Specifications: Robotic Heads

| Parameter | "Parallel" Computer | "Regular" Computer |
|-----------------------------------------------------|------------------------------------------------------------------------------------------------------------------|--------------------|
| CPU | Intel 4th Generation Core i5-4402E | Intel Atom N2600 |
| Chipset | Intel QM87 Express | Intel NM10 |
| RAM | 4GB | |
| SSD Disk | 32GB | |
| OpenCL Support | Yes | No |
| Supported Operating Systems | Linux (Ubuntu preinstalled by default), Windows | |
| Input voltage | 18-36 VDC | |
| Nominal voltage | 24 VDC | |
| Power Consumption | 30-50W depending on the chosen configuration | |
| Weight | 2.95-4.30 kg depending on the chosen configuration | |
| Protection rating | IP68 Dust-proof Watertight | |
| Environmental temperature range | -20C ... +50C with additional limitations applied by specific payloads. optional: extended temperature range | |
| Range of remote control, - line of sight | several kilometers | |
| - indoors or in urban environments | within a few hundred meters | |
| Radio frequency | 902-928 MHz or 2.4 GHz | |
| Laser scanner range | Up to 4.5 m | |
| Video cameras | an optical zoom camera (x24 zoom), a pair of forward looking cameras for stereo vision, a rear view camera | |
| Thermal Vision Camera | optional, external | |
| Sensors for Automatic Navigation and Mapping | Laser Scanner, GPS/GLONASS receiver, Stereo Vision, 6DOF IMU (MEMS) | |
| Headlight | High-intensity white headlight | |
| Number of hardpoints for external payloads | 1 | |
| Bus for connecting external payloads | CAN Ethernet USB | |

Dimensions of Robotic Head



Dimensions of Desktop Robotic Head

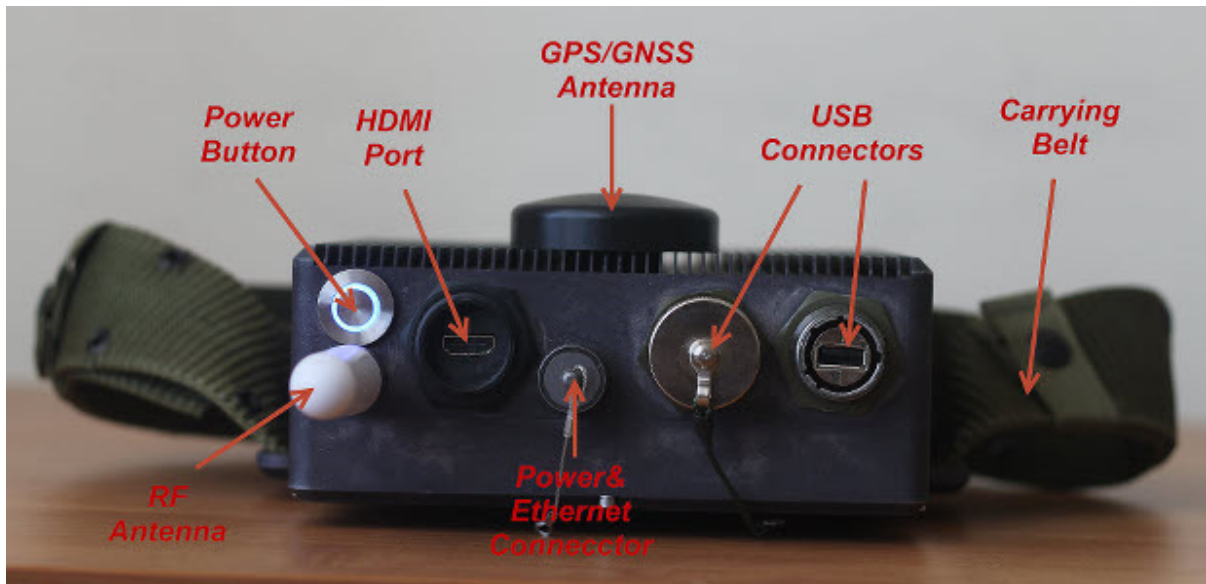


Operator Control Unit (OCU)



A portable operator control unit, or OCU, complements Servosila Robotic Heads with a remote control functionality. The unit is a passively cooled computer with a radio modem and a battery included into a water-tight enclosure.

The unit comes with ports for a joystick and either a virtual reality goggles or a portable handheld display. Please note that in order to use the OCU, the robotic head must be equipped with a radio modem. The OCU also allows to control the robot via a cable.



Specifications: OCU

| Parameter | Value |
|---------------------------------------------|--------------------------------------------------------------------------------------------------------------------|
| CPU | Intel Atom N2600 |
| Chipset | Intel NM10 |
| RAM | 4GB |
| SSD Disk | 32GB |
| OpenCL Support | No |
| Supported Operating Systems | Linux (Ubuntu preinstalled by default), Windows |
| Single charge operation | 5-6hrs |
| Weight | 4.9 kg with all accessories |
| Protection rating | IP68 Dust-proof Watertight |
| Environmental temperature range | -20C ... +50C with additional limitations applied by specific payloads. optional: extended temperature range |
| Range of remote control, - line of sight | several kilometers |
| - indoors or in urban environments | within a few hundred meters |
| Radio frequency | 902-928 MHz or 2.4 GHz |
| Sensors | GPS/GLONASS receiver (optional) |
| Bus for connecting external payloads | HDMI Ethernet USB |

About Servosila

Servosila is a technology company that designs, produces and markets a range of mobile robots, servo drives, and robotic control systems as well as software that makes the mobile robots intelligent.

www.servosila.com

www.youtube.com/user/servosila/videos

